



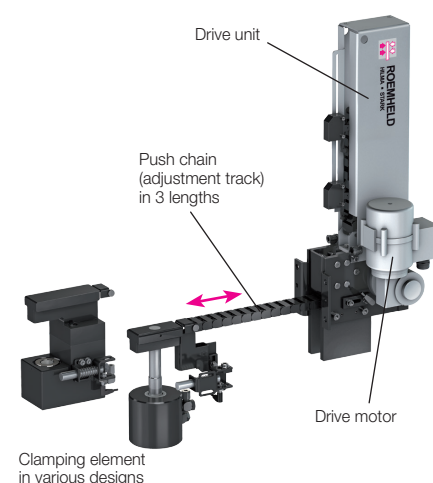
Rapid Clamping Systems Flexline with Push Chain

Flexible selection of clamping element, T-slot and adjustment track electrically or pneumatically driven



Advantages

- 9 different clamping elements
- 4 different T-slots
- 3 different adjustment tracks
- Electrical or pneumatic drive motor
- Easy to service, easily exchangeable modular assemblies ensure high availability of parts
- Technical design and finished drawing in just a few minutes
- Highly flexible, low-maintenance hydraulic hoses with high burst pressure



Application

Rapid clamping systems are used for the automatic clamping of dies of varying sizes on the press ram.

Description

The electro-mechanical / electrically or pneumatically driven push chain moves the clamping element attached to the rapid clamping system automatically from the parking position to the clamping position at the clamping edge and then back to the parking position.

The T-slot of the machine serves as the guide for the push chain and clamping element. The push chain also serves as the energy chain for accommodating the hydraulic and electric lines of the clamping element.

Versions

Flexline rapid clamping systems can be supplied in the following variants:

- **Clamping elements**
Hollow piston cylinders, clamping cylinders with locking mechanism, spring clamping cylinders or sliding clamps
- **T-slots** 28, 32 or 36 mm or 1 1/16"
- **Adjustment tracks** (tracks of the clamping element) 660, 820 or 1100 mm
- **Drive motor** electrically or pneumatically driven
- **Optional position monitoring** (adjustable)
micro switch for "end position" and "intermediate position"
- **Position monitoring of the "die position"** attached on the left or right hand side
- **Chain case** in galvanised design or painted individually at customer's request
- **Option: design with UL-compliant components**
- **Various Harting connectors** selectable for motor current and monitoring signals
- **Option: socket housing** for assembly to the machine

Technical data

T-slot	28 mm and 36 mm (DIN 650) / 32 mm (similar to DIN 650) and 1 1/16"
Adjustment speed	150 mm/s
Option drive motor	Various three-phase motors Technical characteristics see page 2 Pneumatic motor Direct current motor 24 V DC Alternating current motor 120 VAC 60 Hz
Motor connection	Harting connector with 500 mm cable length
Monitoring connection	Harting connector with 500 mm cable length
Monitoring:	
1. Parking position	inductive sensor 24 (10–30) V DC
2. Die position	inductive sensor 24 (10–30) V DC
Option:	
3. "End position" (end of chain)	micro switch
4. "Intermediate position"	micro switch
Hydraulic connection	8 mm pipe socket with union nut M 16x1.5 (500 mm hose length)
Operating temperature	max. 70 °C
Part no.	8228 (basic version)

Application example



Product selection

Selection scheme

You can configure the desired product variant yourself. You are provided with a dimension drawing for the selected configuration and can send us your chosen configuration directly for an offer to be prepared.

Clamping element	Dimensions D x L	Clamping force	Operating pressure	Total stroke S	Clamping stroke St	Oil volume clamping/unclamping
☐ Hollow piston cylinder, double acting	Ø 95 x 88	104 kN	400 bar	12 mm	8 mm	2.6/2.6 cm³/mm
☐ Hollow piston cylinder, single acting	Ø 90 x 105	104 kN	400 bar	12 mm	8 mm	2.6/ – cm³/mm
☐ Hollow piston cylinder, double acting	Ø 105 x 88	100 kN	245 bar	12 mm	8 mm	4.1/4.1 cm³/mm
☐ Hollow piston cylinder, single acting	Ø 100 x 112	100 kN	245 bar	12 mm	8 mm	4.1/ – cm³/mm
☐ Clamping cylinder, double acting, with locking	Ø 100 x 128	100 kN	100 bar	8 mm	4 mm	31/31 cm³/mm (22 cm³ for adjustment stroke 0–3 mm)
☐ Spring clamping cylinder, single acting	Ø 120 x 134	100 kN	260 bar	7 mm	1 mm	– /7.9 cm³/mm
☐ Sliding clamp, double acting	80 x 75	78 kN	400 bar	12 mm	8 mm	2/1.5 cm³/mm
☐ Sliding clamp, single acting	80 x 75	78 kN	400 bar	12 mm	8 mm	2 cm³/mm
☐ Double piston sliding clamp, double acting	140 x 70	100 kN	400 bar	23 mm	19 mm	2.5/1.9 cm³/mm

Slot width a	max. track of the clamping element V
☐ 28 mm (DIN 650)	☐ 660 mm (H = 574 mm)
☐ 32 mm	☐ 820 mm (H = 654 mm)
☐ 36 mm (DIN 650)	☐ 1100 mm (H = 794 mm)
☐ 1 1/16" (27 mm)	

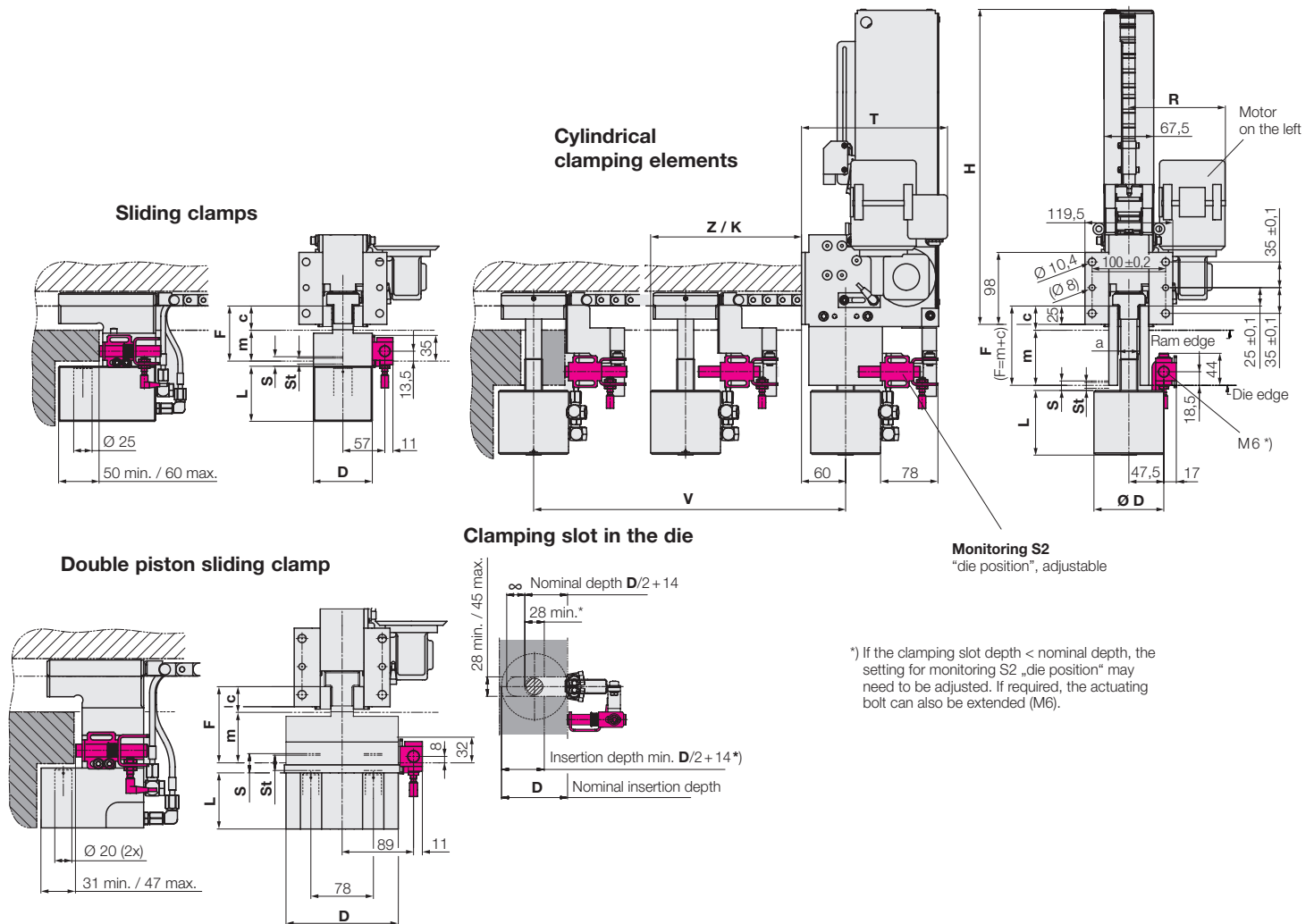
Motor	☐ on the left	☐ on the right	☐ at the rear	R			T		
				Motor on the left/on the right/at the rear			Motor on the left/on the right/at the rear		
☐ 400 V ± 10 %, 50 Hz, 3~ AC [0.37 A, 45 W, ~150 mm/s] (UL compliant)				141 mm	141 mm	81.5 mm	206.5 mm	223.5 mm	340 mm
☐ 420–480 V ± 10 %, 60 Hz, 3~ AC [0.3-0.37 A, 45 W, ~150 mm/s] (UL compliant)				141 mm	141 mm	81.5 mm	206.5 mm	223.5 mm	340 mm
☐ 380 V ± 10 %, 50 Hz, 3~ AC [0.34 A, 45 W, ~150 mm/s] (UL compliant)				141 mm	141 mm	81.5 mm	206.5 mm	223.5 mm	340 mm
Option									
☐ Pneumatic motor [6 bar, 0.36 m³/min]				119 mm	119 mm	59 mm	188 mm	206 mm	306 mm
☐ Direct current motor 24 VDC [5 A, 60 W]				119 mm	119 mm	59 mm	188 mm	206 mm	306 mm
☐ Alternating current motor 120 VAC, 60 Hz, 1~ AC [0.89 A, 45 W, ~150 mm/s] (UL compliant)				130 mm	130 mm	70.5 mm	199.5 mm	217 mm	333 mm

Position monitoring	Chain case
☐ Die position S2 - on the left	☐ galvanised, unlacquered
☐ Die position S2 - on the right	☐ lacquered RAL XXXX
☐ End position S3 + spec. of dimension K	
☐ Intermediate position S4 + spec. of dimension Z	

Harting connector for motor and position monitoring	
☐ Harting HAN modular 3x5 ES	Pin assignment type 2290
☐ Harting HAN 3 HvE / HAN 10 E	☐ Harting HAN 3 HvE / HAN 10 E "2290"
☐ Harting HAN 6 ES / HAN 10 ES	☐ Harting HAN 6 ES / HAN 10 ES "2290"
☐ Counterparts included in the delivery (selectable option: yes/no)	
Option	
☐ Harting HAN 10 ES for pneumatic motor	
☐ Harting HAN 10 ES for 24 VDC motor	
☐ Harting HAN 6 ES / HAN 10 ES (for single-phase alternating current motor 115 VAC, 60 Hz)	

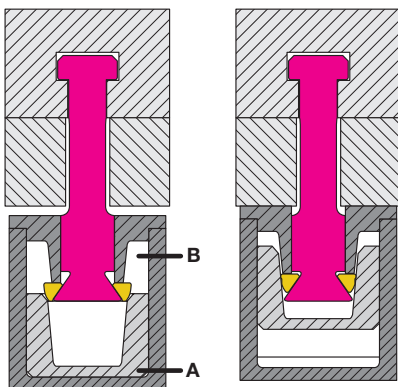
Clamping dimension Specification of clamping dimension F (±St/2) in [mm]	
F = mm	F = c + m (m = die clamping edge, c = web height of T-slot)

F min. 70 mm, max. 128 mm for hollow piston cylinder
 F min. 70 mm, max. 112 mm for spring clamping cylinder and clamping cylinder with locking
 F min. 72 mm, max. 128 mm for sliding clamp + T-slot 28 + 1 1/16"
 F min. 77 mm, max. 128 mm for sliding clamp + T-slot 32
 F min. 82 mm, max. 128 mm for sliding clamp + T-slot 36
 F min. 70 mm, max. 128 mm for double piston sliding clamp + T-slot 28 + 1 1/16"
 F min. 72 mm, max. 128 mm for double piston sliding clamp + T-slot 32
 F min. 72 mm, max. 128 mm for double piston sliding clamp + T-slot 36



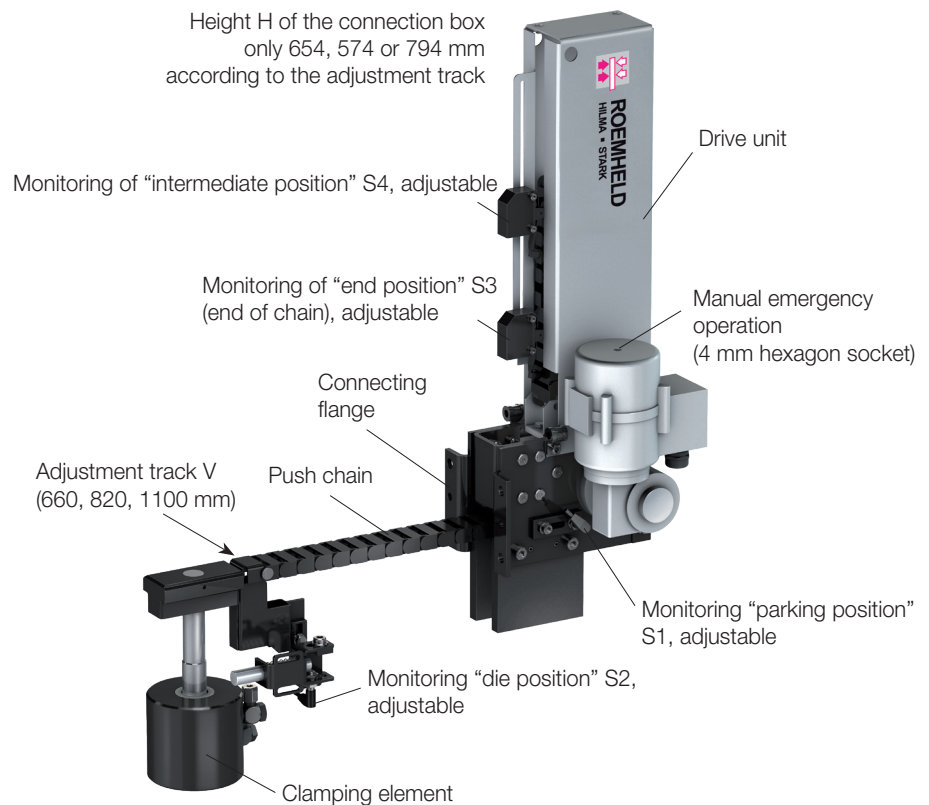
Clamping cylinder, double acting, with locking

Unclamping position Clamping position

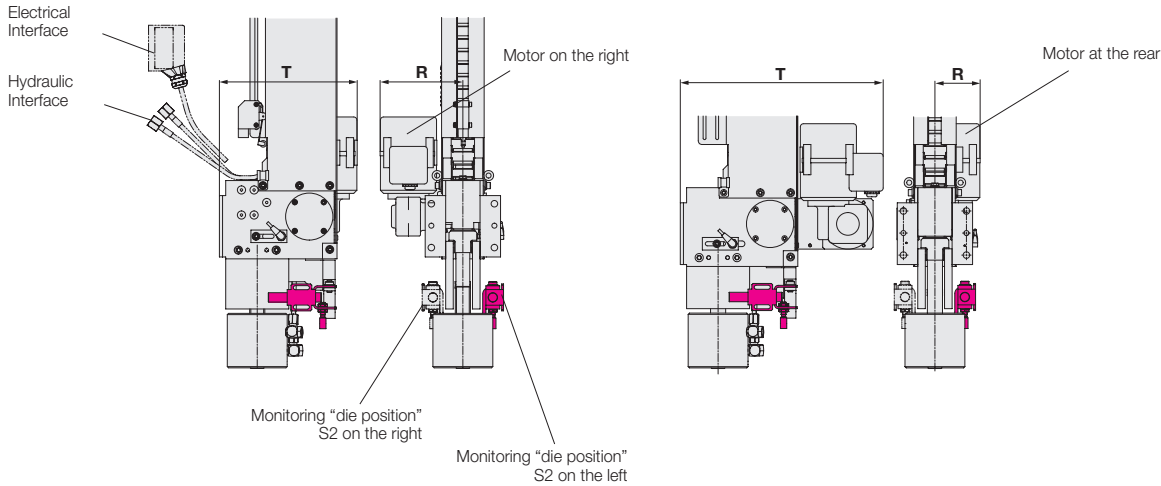


Functioning

To clamp, apply pressure to port A. The clamping element is moved by means of the integrated wedge mechanics to the edge of the die in a rapid adjustment stroke. After generating clamping force of 100 kN with only 100 bar operating pressure, the clamping position is then mechanically secured in a self-locking manner, so that the clamping force is retained completely, even in the event of pressure loss. For safety reasons, it is recommended to maintain the hydraulic pressure. To unclamp, depressurise port A and apply pressure to port B. The mechanical lock is released and the clamping element moves to the unclamping position.



Interfaces



Electrical interface

Harting connector for motor + position monitoring
Pin assignment and connector version see circuit diagram
(special version or without connector on request)

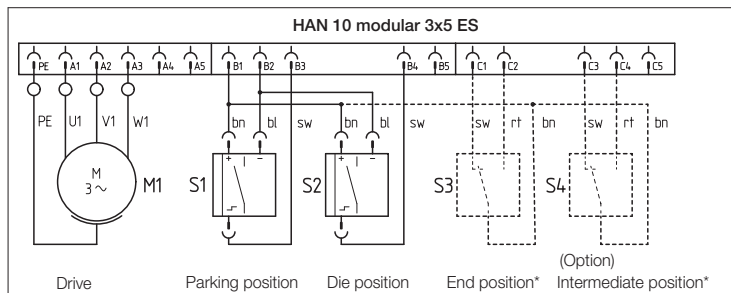
Pneumatic interface (air motor)

Port R to move the clamp forward (to the die)
Port L to move the clamp backward (to the parking station)
Connecting thread $G \frac{1}{4}$ (plug-in connectors included in the delivery)
Operating pressure 6 up to 7 bar
Air supply hose $\varnothing$ LW 6 mm (external $\varnothing$ 8 mm)

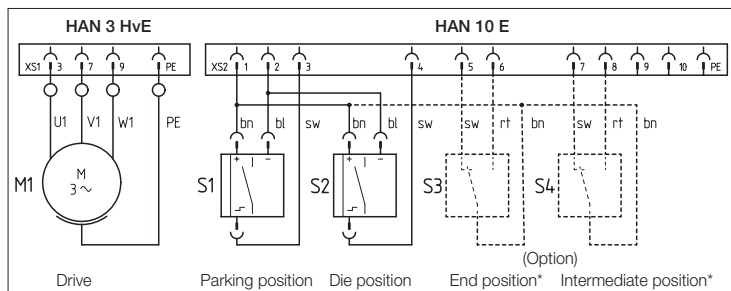
Hydraulic interface

Port A for clamping
Port B for unclamping
Standard: M16x1.5 union nut
Pipe connection $\varnothing$ 8 mm

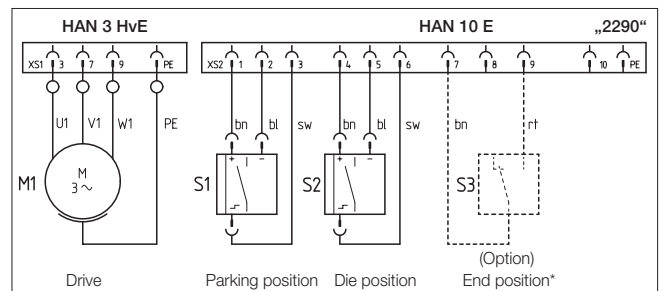
Pin assignment of the Harting connector versions



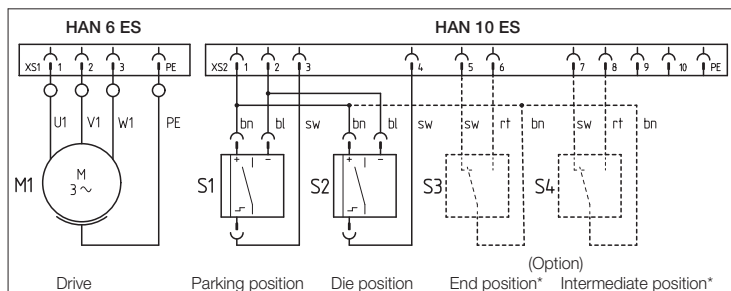
*) not actuated in * position!



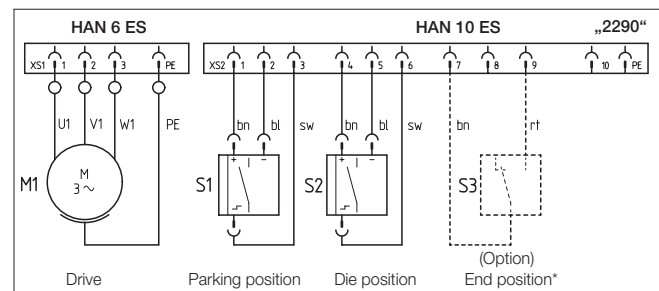
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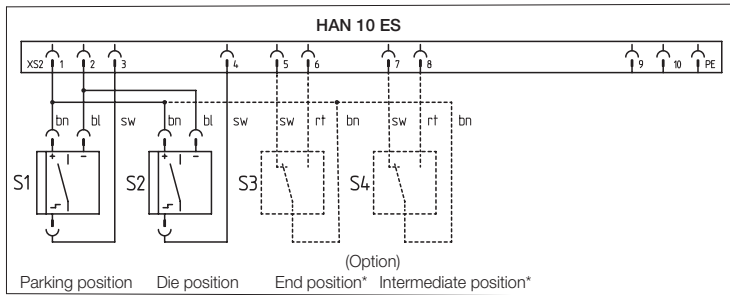


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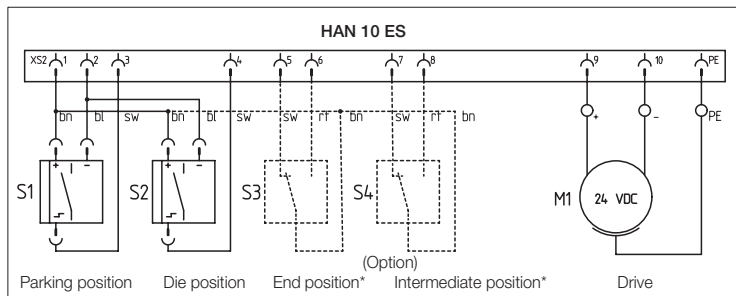
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Pneumatic motor



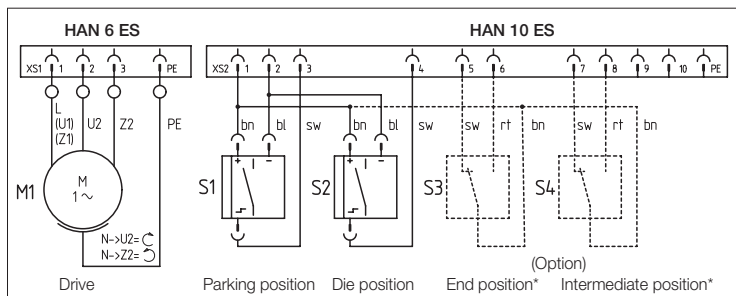
* not actuated in * position!

Direct current motor 24 V DC



* not actuated in * position!

Single-phase alternating current motor 120 V AC 60 Hz



* not actuated in * position!

Special versions of the rapid clamping system

Please contact us if your individual clamping task is not covered by the options available with "Flexline". In many cases, we will be able to fulfill your requirements with a customised special version which deviates only slightly from the standard design.

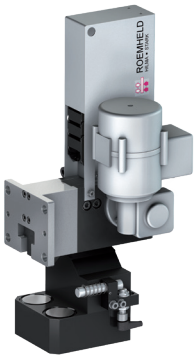
Possible special versions:

- Clamping solutions for tight spaces
- Special mounting hole pattern
- Different T-slot dimension (e.g. T-slot 22)
- Adapted track V (e.g. > 1100 mm)
- Clamping elements with for example:
 - special clamping force
 - specific operating pressure
 - modified clamping stroke St
 - modified clamping dimension F
 - modified shape
 - different mode of operation
- Other motor voltage or other drive principle
- Special options for electric or hydraulic connections
- Components of certain manufacturers or specifications
- Additional requests and customer-specific requirements ...

Examples of possible special versions

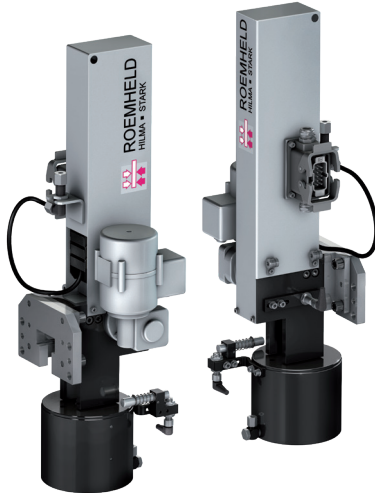
Special sliding clamp with two clamping pistons

- short track



Adaptor plate with special mounting hole pattern

- special electric and hydraulic connection

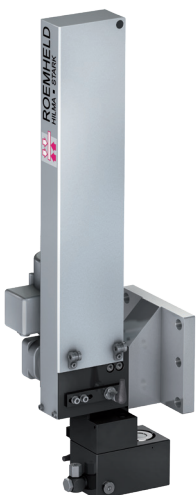


Long track with special low profile chain case

- additional position monitoring



Special flange plate with special mounting hole pattern



Additional extension bracket with new parking position to overcome major obstruction on the press

